



**Prince Mohammad Bin Fahd University**  
**College of Engineering**  
**Department of Electrical Engineering**

# **WHEELCHAIR +**

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**May 17, 2022**



# OUTLINE

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- ❖ **Project Definition**
- ❖ **Project Objectives**
- ❖ **Project Specifications**
- ❖ **Project Constraints & Standards**
- ❖ **Project Architecture**
- ❖ **Planning**
- ❖ **Background**
- ❖ **Design: Subsystems & Components**
- ❖ **Testing**
- ❖ **Project Mgmt. & Team Work**
- ❖ **Impact of Project**
- ❖ **New Skills Acquired/Applied**
- ❖ **Completed Work**
- ❖ **Remaining Work**
- ❖ **Total Cost**
- ❖ **References**

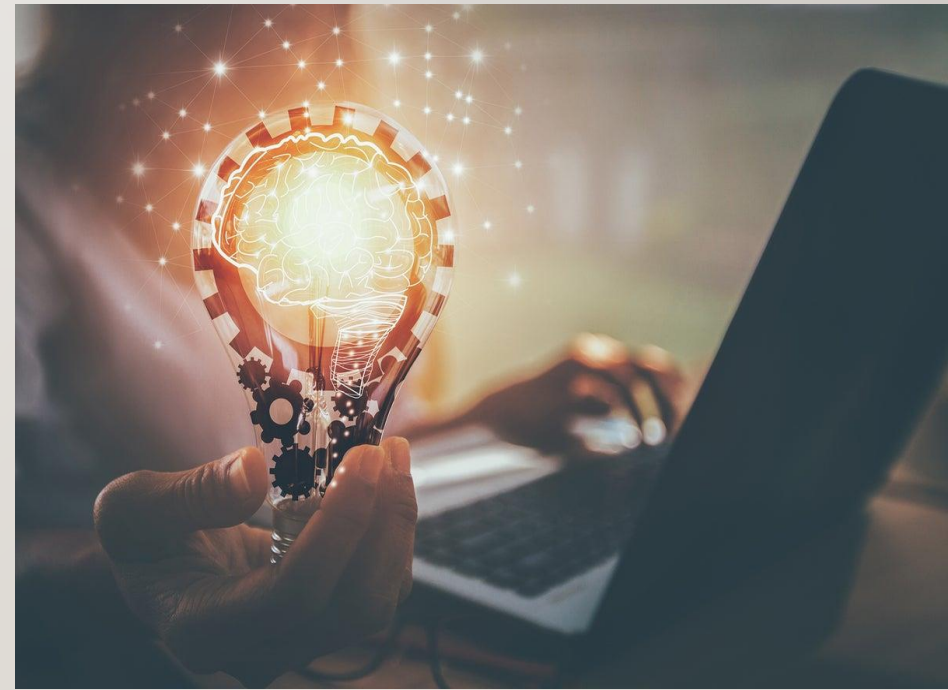


# ★ PROJECT DEFINITION

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To enhance the electric wheelchair for people with special needs & elderly who are unable to move on their own.

The wheelchair will have features to control by **specific voice commands**, **Joy Stick** i.e. **Dual Functionality** + features like **obstacle avoidance** & **GPS tracking** that the chair will understand and implement.



# ★ PROJECT OBJECTIVES



- ❖ Increase features to contemplate ones who cannot control the wheelchair individually & make the person Independent.
- ❖ Efficiently adopting the use of audio signals to save time, conserving energy and provide self-control.
- ❖ Provide adequate and automatic safety measures to ensure the protection of the user.
- ❖ Enabling the wheelchair to function both manually and automatically with maximum efficiency and minimum errors.

# PROJECT SPECIFICATIONS

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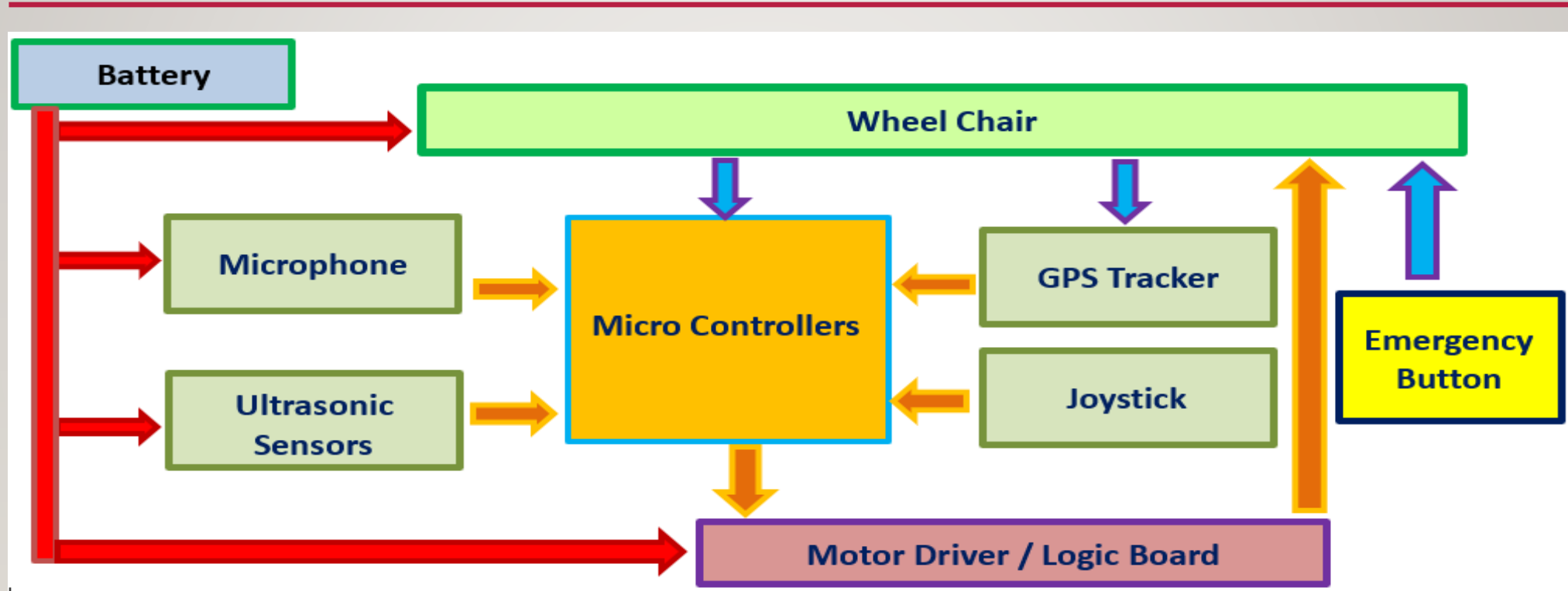
- ❖ Recognizes specific audio input through the microphone for movement.
- ❖ Has dual functionality i.e. controlled by both voice & joystick.
- ❖ Traces location of the wheel chair to keep the caretakers aware through GPS.
- ❖ Automatically detects & stops if any obstacles are in the way through sensors.
- ❖ Has an emergency button to halt operations if any malfunction/problem occurs.
- ❖ Has a sitting space for 1 person & weight capacity of up to 100 kg.
- ❖ Estimated internal power supply 24V, DC Lithium-Ion battery.

# ★ DESIGN CONSTRAINTS & STD.S

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- ❖ (Social) Privacy: People think/believe they will be spied upon by the mic.
- ❖ (Skills) Lack of Knowledge: People lack knowledge to operate smart devices properly.
- ❖ (Financial) Budget: Total cost varies between 4-5 thousand SAR.

# ★ PROJECT ARCHITECTURE



# ★ PLANNING

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- ❖ Did we verify the project feasibility?
- ❖ Did we verify that all components will be available locally or can be ordered within a reasonable time?
- ❖ Did we verify that the required testing can be performed at PMU Labs (instruments and technical help availability?)
- ❖ If not where can we get help, test .....

# ★ BACKGROUND



## ➤ **Voice Controlled Functions**

- ❖ Gives ability to control a wheelchair without the need of hands.
- ❖ The person can move independently.

## ➤ **Automatic Obstacle Avoidance**

- ❖ Helps the wheelchair to avoid obstacles automatically & efficiently.
- ❖ The person can move very safely.

## ➤ **GPS Tracking**

- ❖ Gives ability to track the wheelchair for safety purposes.
- ❖ Loved ones stay aware.

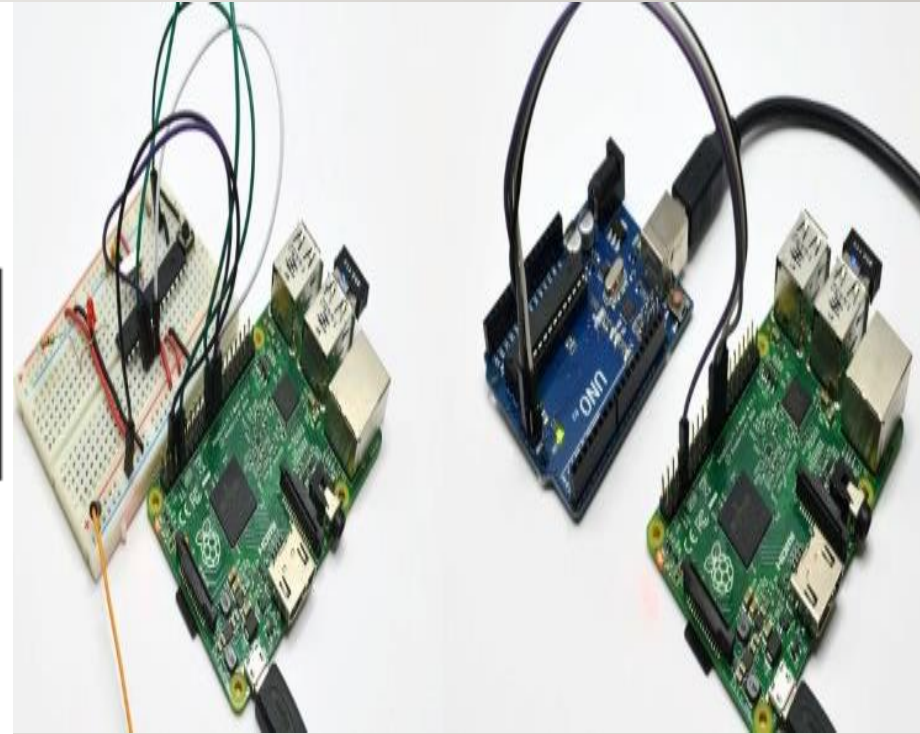
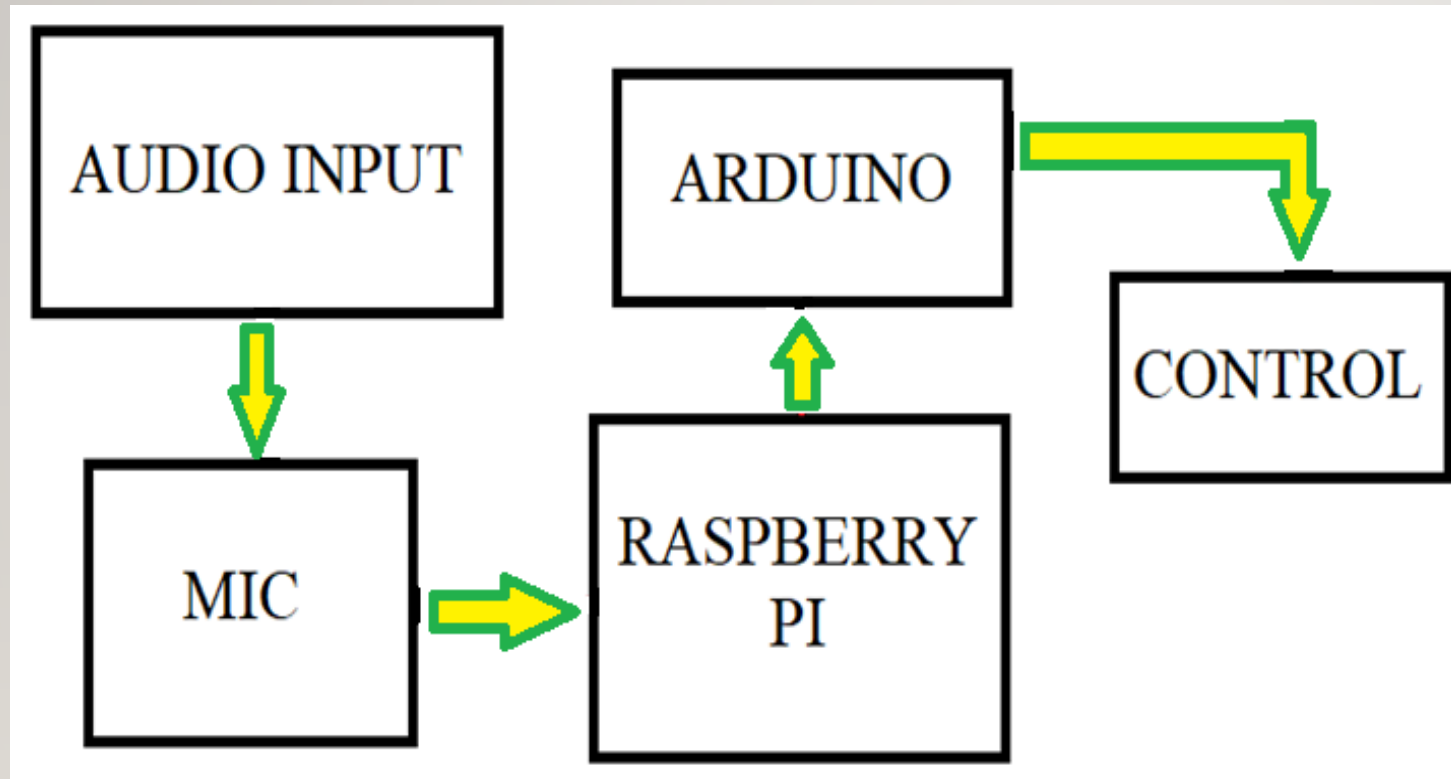
## ➤ **Multi Layer Control**

- ❖ Enables the wheelchair to be controlled by both audio & joystick.
- ❖ Minimizes chances of malfunction.

# ★ DESIGN: BASE



# ★ DESIGN: SUBSYSTEM 1

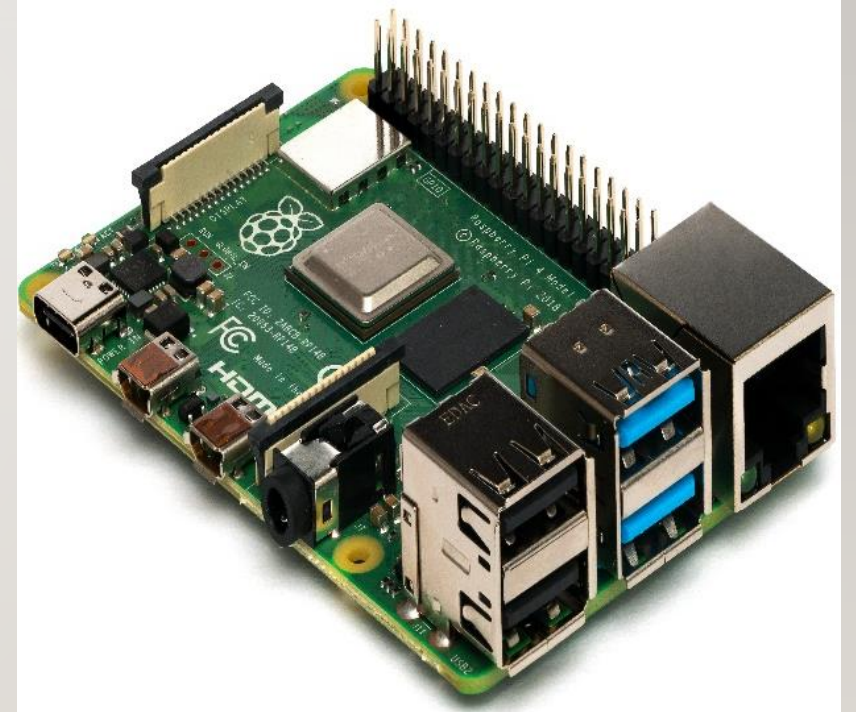
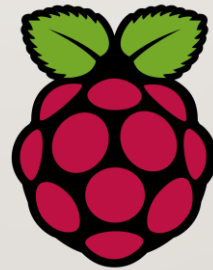


# ★ DESIGN: MICROCONTROLLER

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❖ **Raspberry Pi**  
**4 Model B**



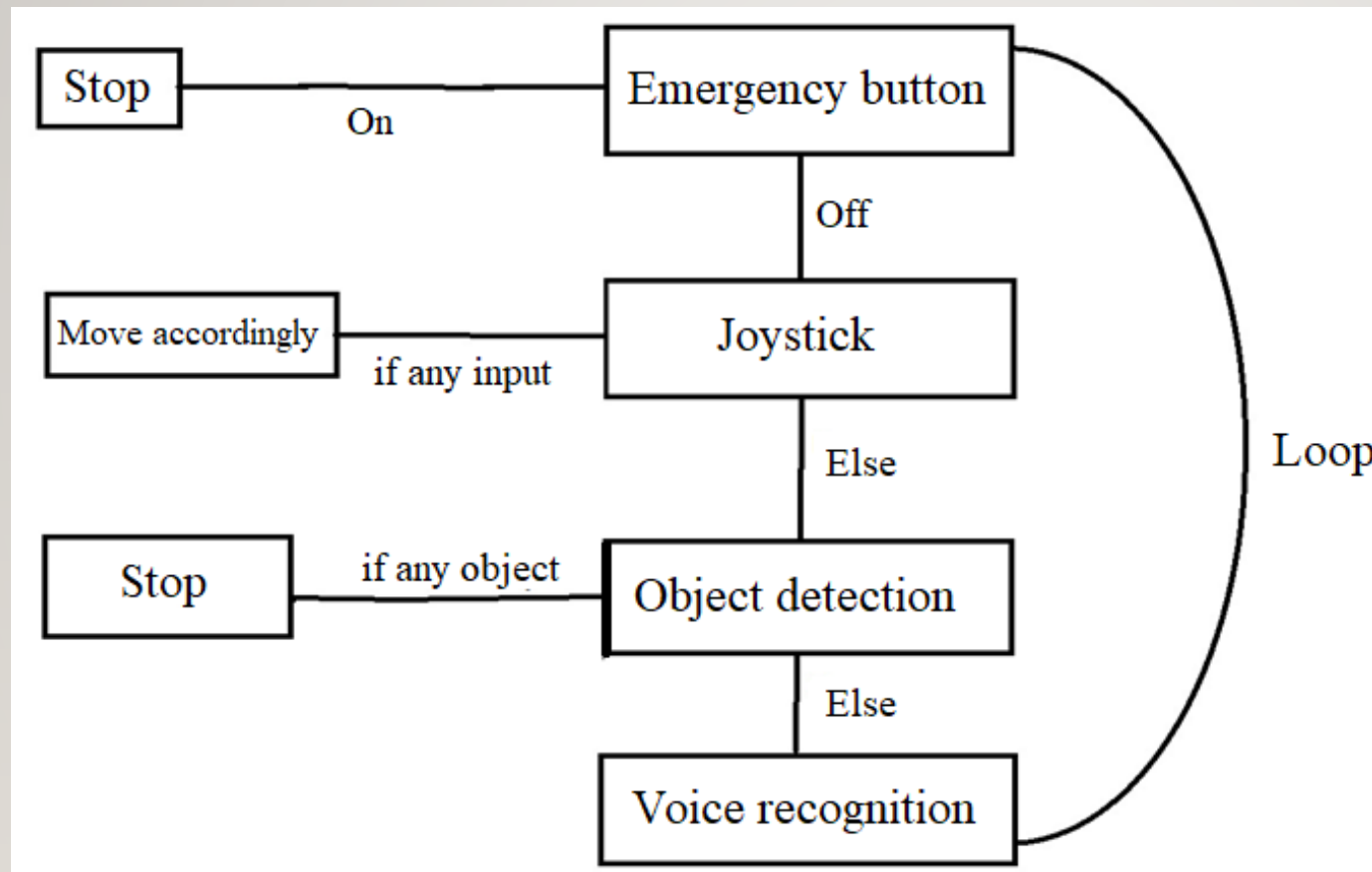
# ★ DESIGN: CODING [PYTHON]

```
File Edit Tabs Help
(venv) pi@raspberrypi:~/Projects/speech $ lsusb
Bus 002 Device 001: ID 1d6b:0003 Linux Foundation 3.0 root hub
Bus 001 Device 004: ID b58e:0005 Blue Microphones
Bus 001 Device 005: ID 05ac:0250 Apple, Inc. Aluminium Keyboard (ISO)
Bus 001 Device 003: ID 05ac:1006 Apple, Inc. Hub in Aluminum Keyboard
Bus 001 Device 002: ID 2109:3431 VIA Labs, Inc. Hub
Bus 001 Device 001: ID 1d6b:0002 Linux Foundation 2.0 root hub
(venv) pi@raspberrypi:~/Projects/speech $ arecord -l
**** List of CAPTURE Hardware Devices ****
card 2: Nano [Yeti Nano], device 0: USB Audio [USB Audio]
  Subdevices: 1/1
    Subdevice #0: subdevice #0
(venv) pi@raspberrypi:~/Projects/speech $ cat /proc/asound/cards
0 [b1          ]: bcm2835_hdmi - bcm2835 HDMI 1
                    bcm2835 HDMI 1
1 [Headphones  ]: bcm2835_headpho - bcm2835 Headphones
                    bcm2835 Headphones
2 [Nano        ]: USB-Audio - Yeti Nano
                    Blue Microphones Yeti Nano at usb-0000:01:00.0-1.4, full speed
(venv) pi@raspberrypi:~/Projects/speech $ cat /proc/asound/modules
0 snd_bcm2835
1 snd_bcm2835
2 snd_usb_audio
(venv) pi@raspberrypi:~/Projects/speech $ sudo nano /usr/share/alsa/alsa.conf
```

```
sr.py - Desktop - Visual Studio Code
sr.py 2 x
sr.py > -
1 import pyaudio
2 import websockets
3 import asyncio
4 import base64
5 import json
6 auth_key = 'YOUR_API_KEY'
7
8 FRAMES_PER_BUFFER = 3200
9 FORMAT = pyaudio.paInt16
10 CHANNELS = 1
11 RATE = 16000
12 p = pyaudio.PyAudio()
13
14 # starts recording
15 stream = p.open(
16     format=FORMAT,
17     channels=CHANNELS,
18     rate=RATE,
19     input=True,
20     frames_per_buffer=FRAMES_PER_BUFFER
21 )
22
23 print('ok')
24 # the AssemblyAI endpoint we're going to hit
25 URL = "wss://api.assemblyai.com/v2/realtime/ws?sample_rate=16000"
26
27 async def send_receive():
28     print(f'Connecting websocket to url ${URL}')
29     async with websockets.connect(
30         URL,
31         extra_headers={
32             'Authorization': f'Bearer {auth_key}'
33         },
34         ping_timeout=None,
35         ping_interval=None
36     ):
37         async for message in stream:
38             data = message.json()
39             print(data)
40
41 asyncio.run(send_receive())
```

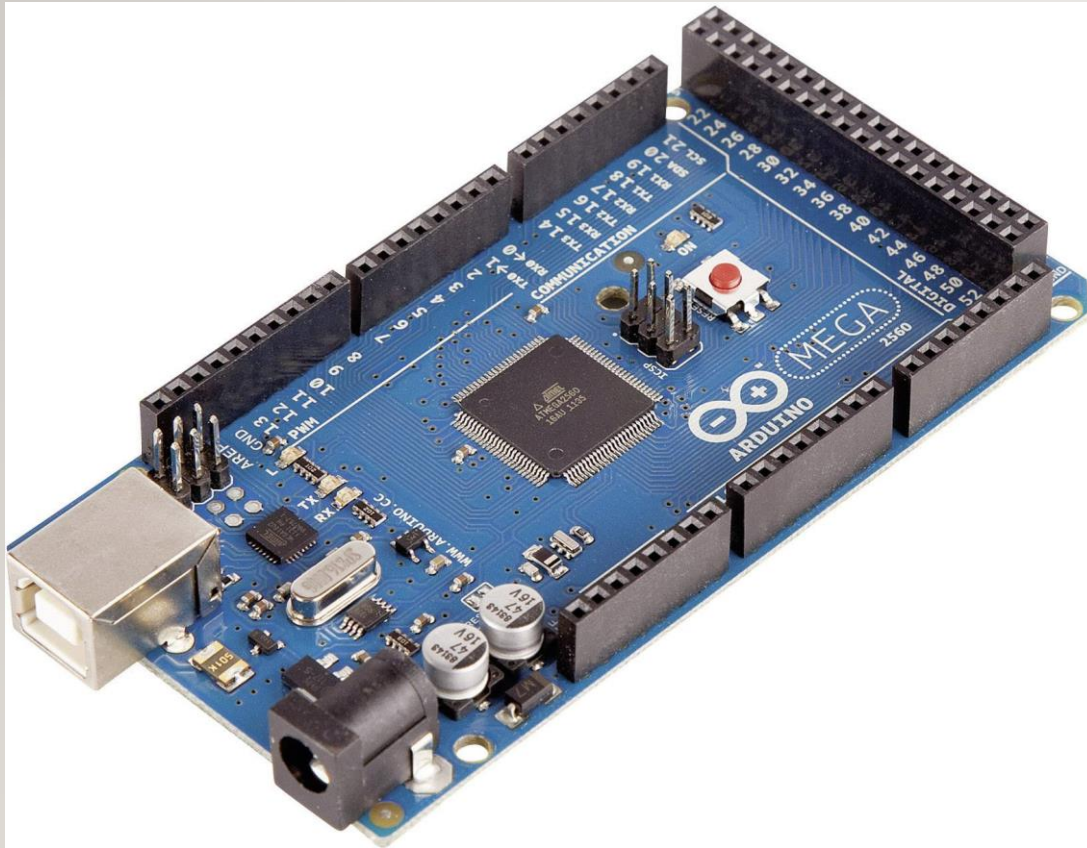
```
pi@raspberrypi:~/Desktop $ . venv/bin/activate
bash: venv/bin/activate: No such file or directory
pi@raspberrypi:~/Desktop $
```

# ★ DESIGN: SUBSYSTEM 2



❖ **Priority Listing**

# ★ DESIGN: MICROCONTROLLER



❖ Arduino Mega 2560

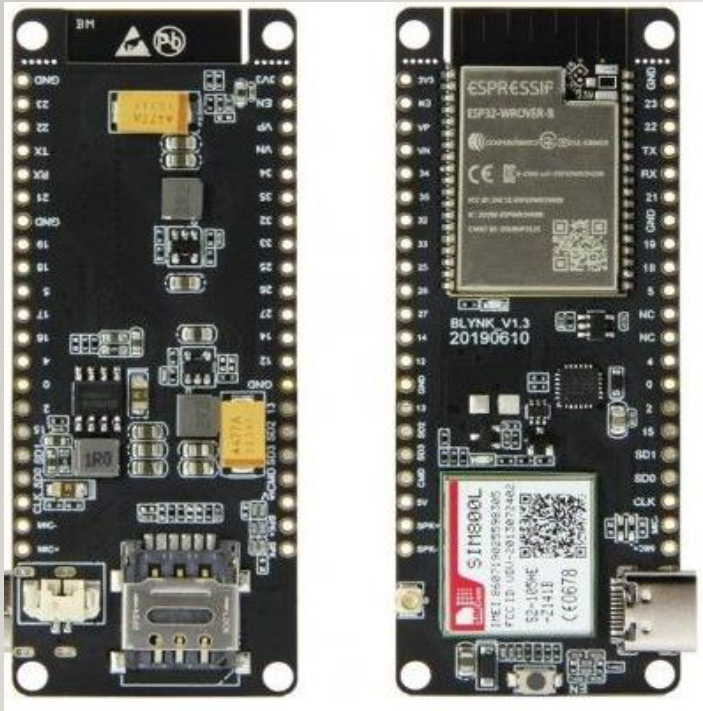


# ★ DESIGN: VOLTAGE DIVIDER

F	Forward	Sets A to 5 volts & B to 2.5 volts
B	Backward	Sets A to 0 volts & B to 2.5 volts
S	Stop	Sets both A and B to 2.5 volts
L	Turn left	Sets A to 2.5 volts & B to 0 volts
R	Turn right	Sets A to 2.5 volts & B to 5 volts



# ★ DESIGN: SUBSYSTEM 3



ESP32 + GSM GPRS COMMUNICATION MODULE



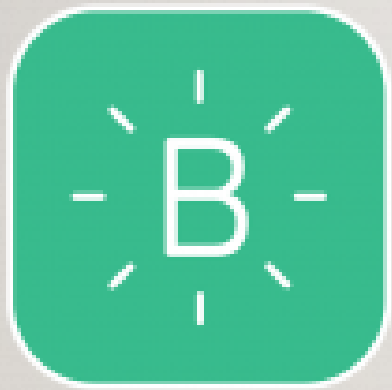
NOE 6M GPS Module



Rechargeable lithium battery 5V

# ★ DESIGN: APPLICATION

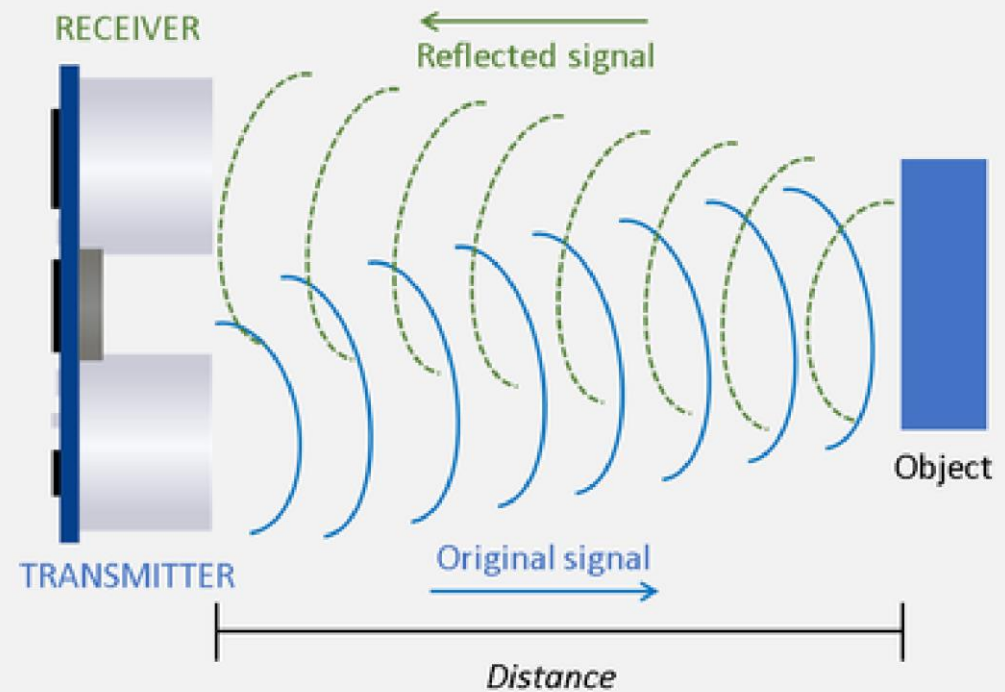
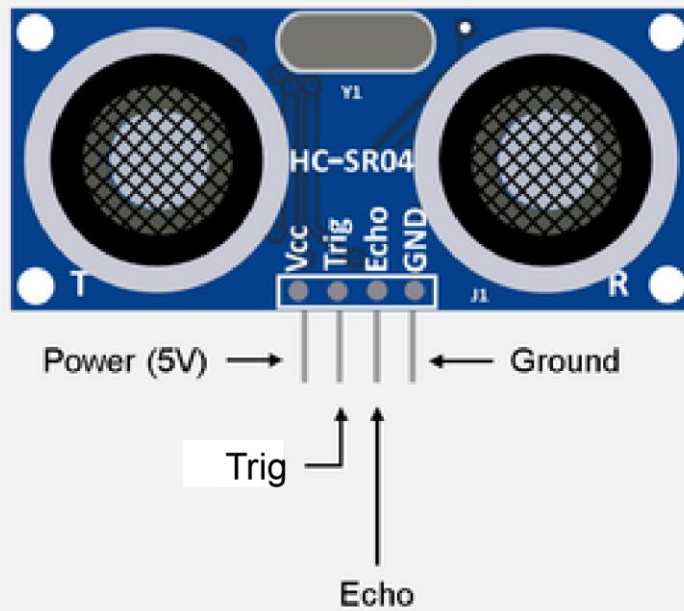
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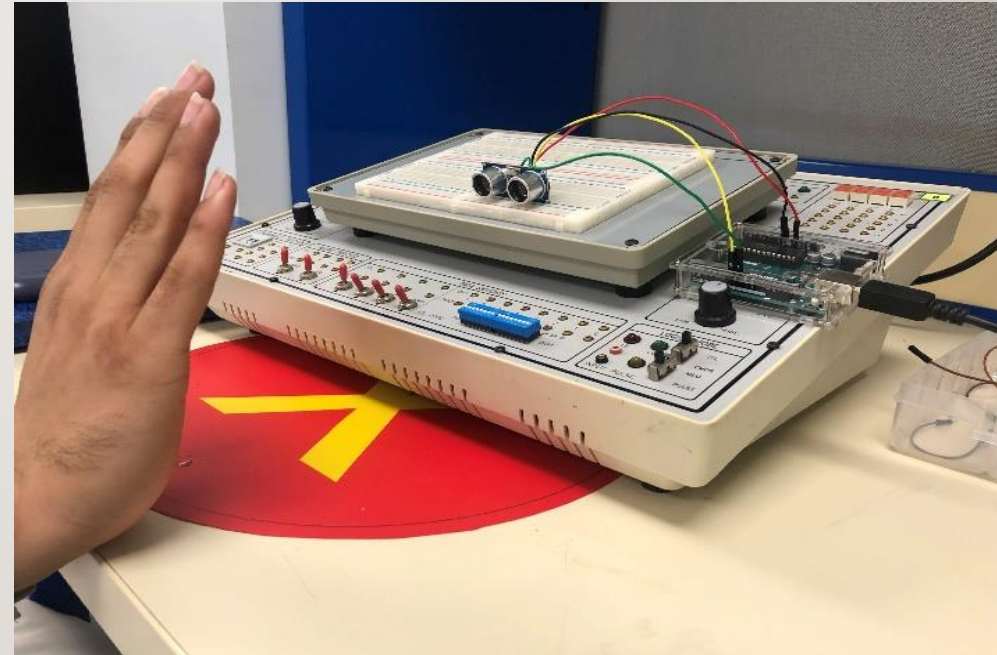
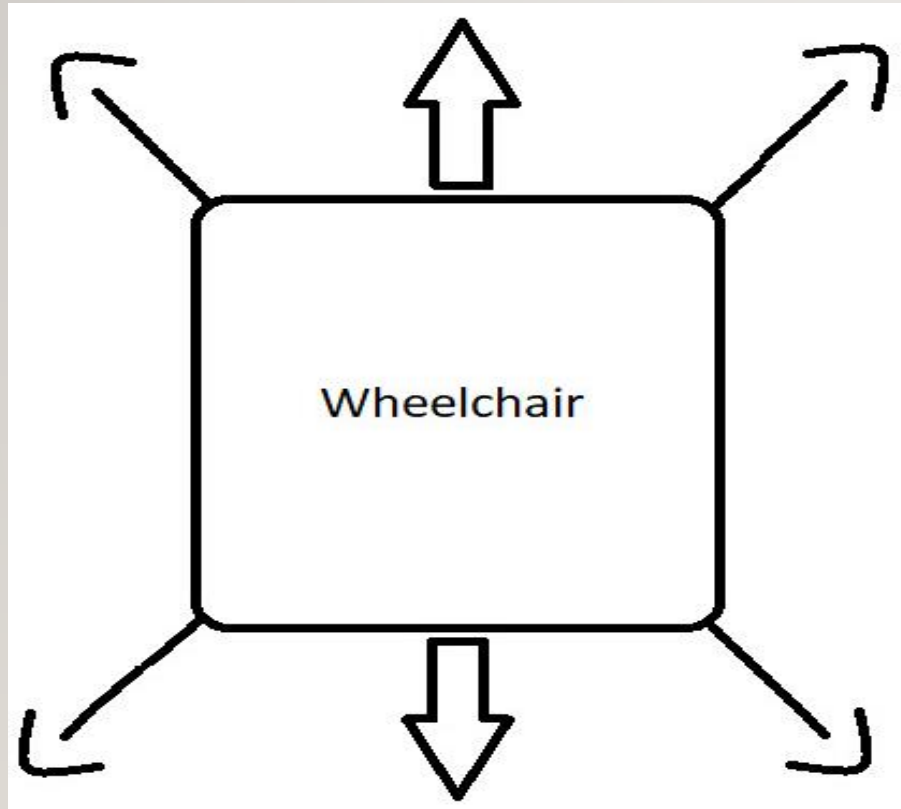
Blynk

❖ **Location Viewing**

# ★ DESIGN: SUBSYSTEM 4



# ★ DESIGN: VIEWING



# ★ PROJECT MGMT. & TEAM WORK

Title: Wheel Chair +		Advisor: Dr. Hirenkumar Kantilal Mewada		Design II (ASSE 3)			Spring 2022												
Ali Khan	201701348	[ AFK ]		Project PLAN & Progress															
Abdullah AlKhalifa	201700776	[ AAK ]		ProgRpt No. 6															
AbdulRahman AlShanqiti	201701387	[ AAS ]		Plan updated (Date): May 17, 2022															
Ali AlQambar	201701325	[ AAQ ]		Instructor: Dr. Sadiq Alhuwaidi															
				Period Highlight:		1	Plan		Actual										
				Actual (beyond plan)		% Complete (beyond plan)													
ACTIVITY	PLAN START	PLAN DURATION	Assigned To	ACTUAL START	ACTUAL DURATION	PERCENT COMPLETE	Periods (Weeks 1-15)												
Update Specifications	1	1	ALL	2	2	100%	█												
Write Plan	1	1	ALL	2	2	100%	█												
Order & Get Remaining Components	2	3	ALL	2	2	100%	█	█											
Complete Subsystem 1 (Voice Control)	2	3	AFK	2	2	100%	█	█											
Test Subsystem 1	3	2	AFK	3	2	100%		█	█										
Design Subsystem 3 (GPS Tracking)	3	3	AAS	3	4	100%		█	█	█									
Test Subsystem 3	4	3	AAS	4	4	100%		█	█	█									
Prepare Midterm Presentation & Video	5	2	ALL	5	3	100%			█	█									
Display Data to End-User	6	5	AAK	6	5	100%			█	█	█								
Design Subsystem 4 (Obstacle Avoidance)	7	3	AAQ	7	3	100%			█	█	█								
Test Subsystem 4	8	3	AAQ	8	2	100%			█	█									
Debug all Programming Code	9	4	ALL	8	4	100%			█	█	█								
Implement Complete Design	10	2	AAK	10	2	100%				█	█								
Integrate all Subsystems	10	2	ALL	11	2	100%				█	█								
Final Testing	12	3	ALL	12	2	100%					█	█							
Prepapre Final Report	12	2	ALL	12	2	100%					█	█							
Prepapre Final Presentation	12	2	ALL	12	3	100%					█	█	█						
Prepare Project Demo	13	3	ALL	13	3	100%						█	█	█					
Submit Rpt/PPT/Brochure/Video...etc.	14	2	AFK, AAS	14	2	100%							█	█					
<b>Progress Details:</b>							<b>Issues (delay, etc.):</b>												
Final Working Getting things ready for Open Day							1- Time Management												

# PROJECT MGMT. & TEAM WORK

<b>Task</b>	<b>Ali Khan</b>	<b>Abdullah Alkhalifa</b>	<b>Ali AlQambar</b>	<b>Abdulrahman</b>
<b>Search &amp; acquire components</b>	<b>25%</b>	<b>45%</b>	<b>5%</b>	<b>25%</b>
<b>Design &amp; implement subsystems</b>	<b>25%</b>	<b>25%</b>	<b>25%</b>	<b>25%</b>
<b>Testing &amp; debugging</b>	<b>25%</b>	<b>25%</b>	<b>25%</b>	<b>25%</b>
<b>Write reports &amp; presentations</b>	<b>45%</b>	<b>25%</b>	<b>5%</b>	<b>25%</b>

# ★ PROJECT MGMT. & TEAM WORK

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## Challenges & Decision making:

- ❖ Balancing between online & on-campus classes + work by staying late or making special visits.
- ❖ Time management & COVID protocols.
- ❖ Delivery delays + technical issues.
- ❖ Extra curriculum activities.



# RISK MANAGEMENT

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<b>Concerning</b>	<b>Events</b>	<b>Threats</b>	<b>Response</b>	<b>Source</b>
<b>Logic board</b>	<b>Short circuit</b>	<b>Inability to function</b>	<b>Fix or get new</b>	<b>Wheelchair</b>
<b>Team members</b>	<b>Illness / Injury</b>	<b>Development &amp; testing delays</b>	<b>Sickness is unpredictable &amp; unavoidable.</b>	<b>Team members</b>

# ★ PROJECT MGMT. & TEAM WORK



# ★ PROJECT MGMT. & TEAM WORK



# ★ IMPACT OF COVID ON PROJECT

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- ❖ Mix between online & on-campus classes caused a very stressful situation for students similar to chaos.
- ❖ Issues with availability of some components due to shipping delays.
- ❖ Difficult to meet & work on the project.
- ❖ Unnecessary rise in prices.



# ★ IMPACT OF PROJECT IN SOCIETY

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- ❖ Moving away from dependency i.e. user becomes independent.
- ❖ Extremely positive impact as it provides features for those who were never given any.
- ❖ Relieved people from worrying about their loved one that cause stress.
- ❖ These features will someday become the basic standard of a wheel chair.

# FUTURE POSSIBILITIES

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- ❖ Simplification of the process by only using the Raspberry Pi.
- ❖ Placement of a camera to monitor the physical state of the user.
- ❖ Emergency Notification Protocol ‘ E.N.P ’
- ❖ Save voice commands to only work for specific people.

# ★ NEW SKILLS ACQUIRED/APPLIED

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- ❖ Learnt & familiarized with Raspberry Pi & its software.
- ❖ Ability to work with the internal circuitry of a complex machine.
- ❖ Process of making professional & technical reports & presentations.
- ❖ Connections between different microcontrollers.
- ❖ Teamwork & problem solving enhancement.



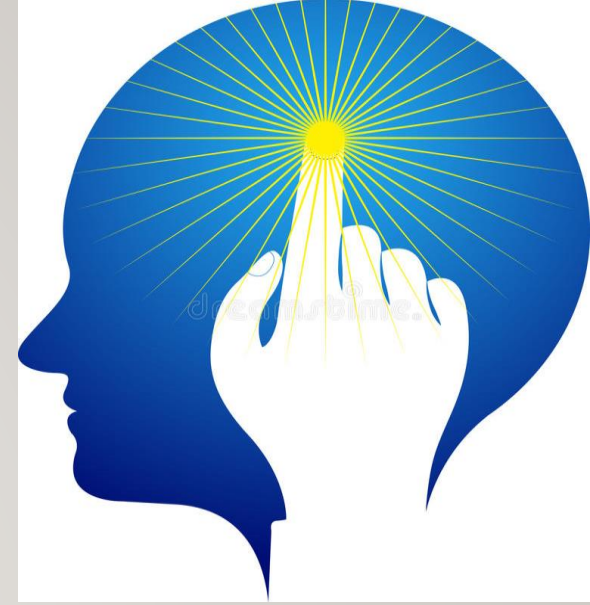
# TOTAL COST

No.	Description	Quantity	Unit Cost (SR)	Total Cost (SR)
1	Electric Wheel Chair	1	3619	3619
2	Microcontroller	2	200	400
3	Mic	1	66	66
4	GPS Tracker	1	200	200
5	Ultrasonic Sensor	12	5	60
6	Fixing Issues	1	300	400
7	Deliverables	1	350	350
8	Misc. Chips & Components	...	...	Approx. 35
<b>Total</b>				<b>5000</b>

# REFERENCES

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- ❖ M. A. Alim, S. Setumin, A. D. Rosli and A. I. C. Ani, "Development of a Voice-controlled Intelligent Wheelchair System using Raspberry Pi," 2021 IEEE 11th IEEE Symposium on Computer Applications & Industrial Electronics (ISCAIE), 2021, pp. 274-278, doi: 10.1109/ISCAIE51753.2021.9431815.
- ❖ S. Umchid, P. Limhaprasert, S. Chumsoongnern, T. Petthong and T. Leeudomwong, "Voice Controlled Automatic Wheelchair," 2018 11th Biomedical Engineering International Conference (BMEiCON), 2018, pp. 1-5, doi: 10.1109/BMEiCON.2018.8609955.
- ❖ D. Cagigas and I. Abascal, "Hierarchical path search with partial materialization of costs for a smart wheelchair", Journal of Intelligent and Robotic Systems, vol. 39, no. 4, pp. 409-431, Apr. 2004.
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- ❖ Katrina Hayward, "Experimental Phonetics" in , Harlow, UK:Pearson, pp. 149, 2000, ISBN 0-582-29137-2.
- ❖ <https://create.arduino.cc/projecthub/muchika/vehicle-tracking-system-based-on-gps-and-gsm-57b814>



ANY

QUESTIONS





THANK YOU

