



Prince Mohammad Bin Fahd University
College of Engineering
Department of Electrical Engineering

Smart Dropbox with OCR

Faisal Aldossary	201700817
Adel Almutairi	201702264
Saad Alzuabi	201502138
Bandar Alghamdi	201602764

Advisor: Dr. Sadiq Alhuwaidi.

Co-Advisor: Dr. Hirenkumar Mewada

May 17, 2022

Outline

- **Project Definition.**
- **Project Objectives.**
- **Project Specifications.**
- **Project Constrains and Engineering Standards.**
- **Project Architecture.**
- **Planning.**
- **Background & Previous Projects.**
- **Design Subsystems and Component Selection.**
- **Testing.**
- **Completed Work.**
- **Project Management & Teamwork.**
- **Risk Management.**
- **Impact of Project.**
- **New Skills Acquired and Applied.**
- **Budget.**
- **References.**

Project Definition

Design a Smart Dropbox that can save time and reduce pressure of deadlines. Smart Dropbox with OCR will have the ability to recognize handwritten papers. Furthermore, it will notify the recipient and the sender when a paper has been received.



Project Objectives

- To design smart Dropbox with OCR, Dropbox, Ultrasonic sensor, OCR and LCD Panel.
- To schedule instructors and students time.
- To reduce students pressure of submitting their assignments.
- To organize deadlines of submission for instructors.
- To arrange assignments/homework in order to be organized.
- Flexibility between students and faculty members in deadline submissions.



Project Specifications

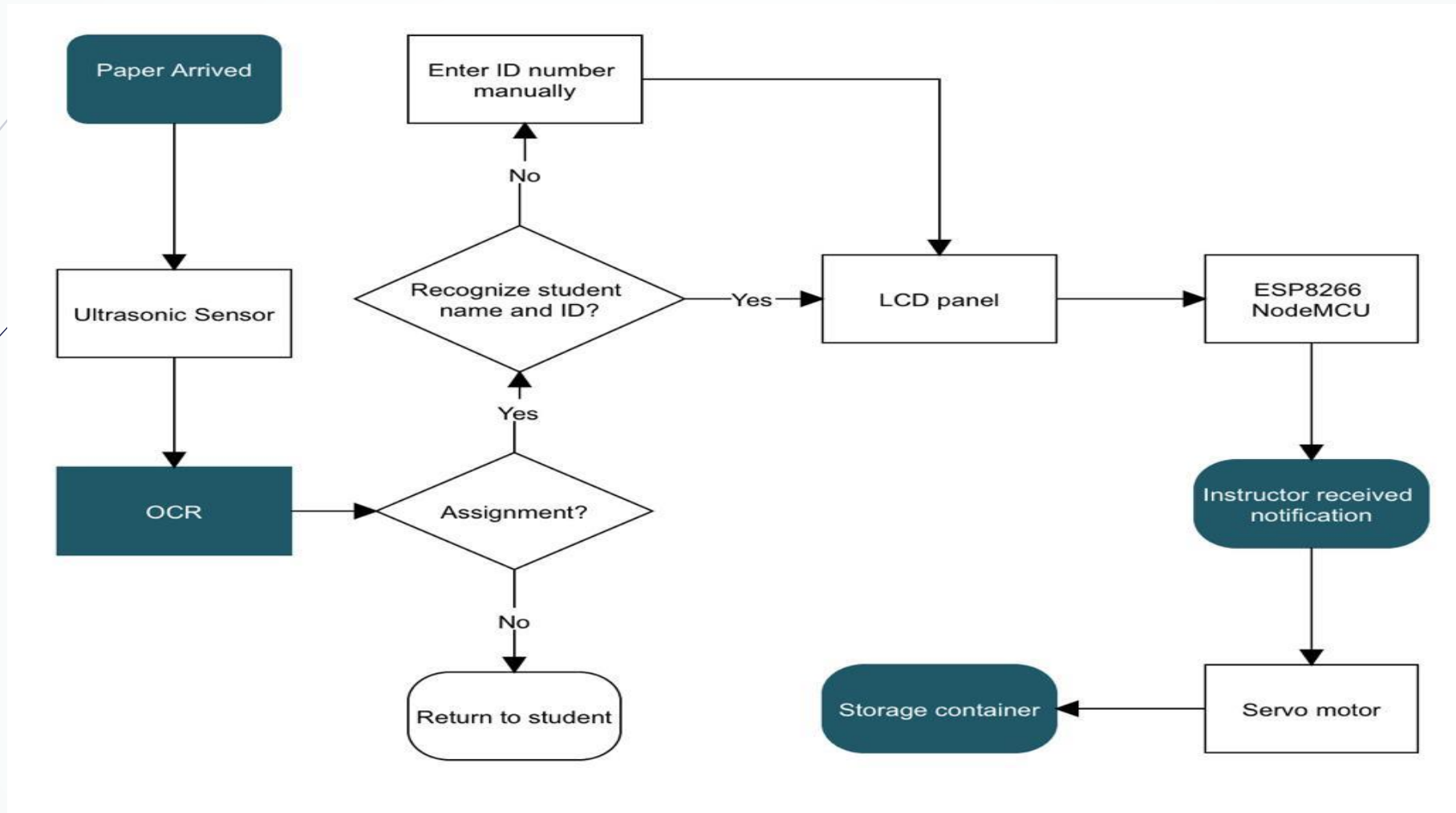
- **Detect** the paper if it's submitted or not by Ultrasonic Sensor.
- **Recognize** handwritten papers by OCR (Optical Character Recognition).
- **Receive** notification by the Smart Dropbox to the student and faculty member when submission received.
- **Operates** the submission in few minutes.
- It has a microcontroller programmed to **control** all sensors inside the Smart Dropbox.
- It has the capacity to **store** up to 3000 papers.

Design Constraints & Standards

6

- Economic (budget).
- Safety.
- Social, culture.

Project Architecture



Planning

- Have verified the efficiency of the topic.
- Choosing the topic, fundamental points, assigned tasks.
- Search for component availability in local stores and online website.
- Examining the selected subsystems.

Background: Problem

- Availability of the instructors.
- Submitting assignments before due date.



Background: Solutions

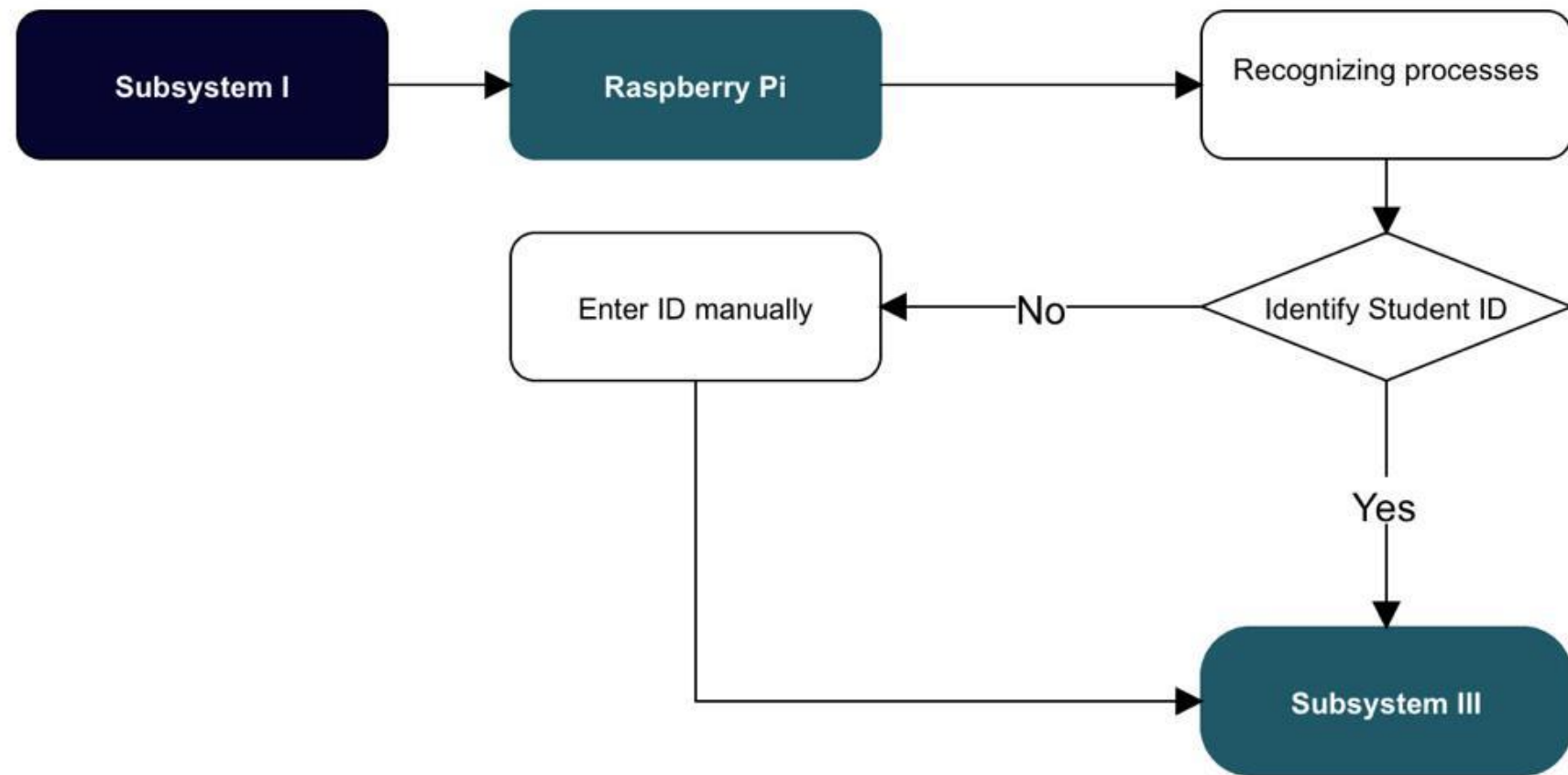
- Instructors will receive a notification with time, date of the submission.
- Smart Dropbox will offer flexibility between instructors and students.



Design Subsystem I: Dropbox Design



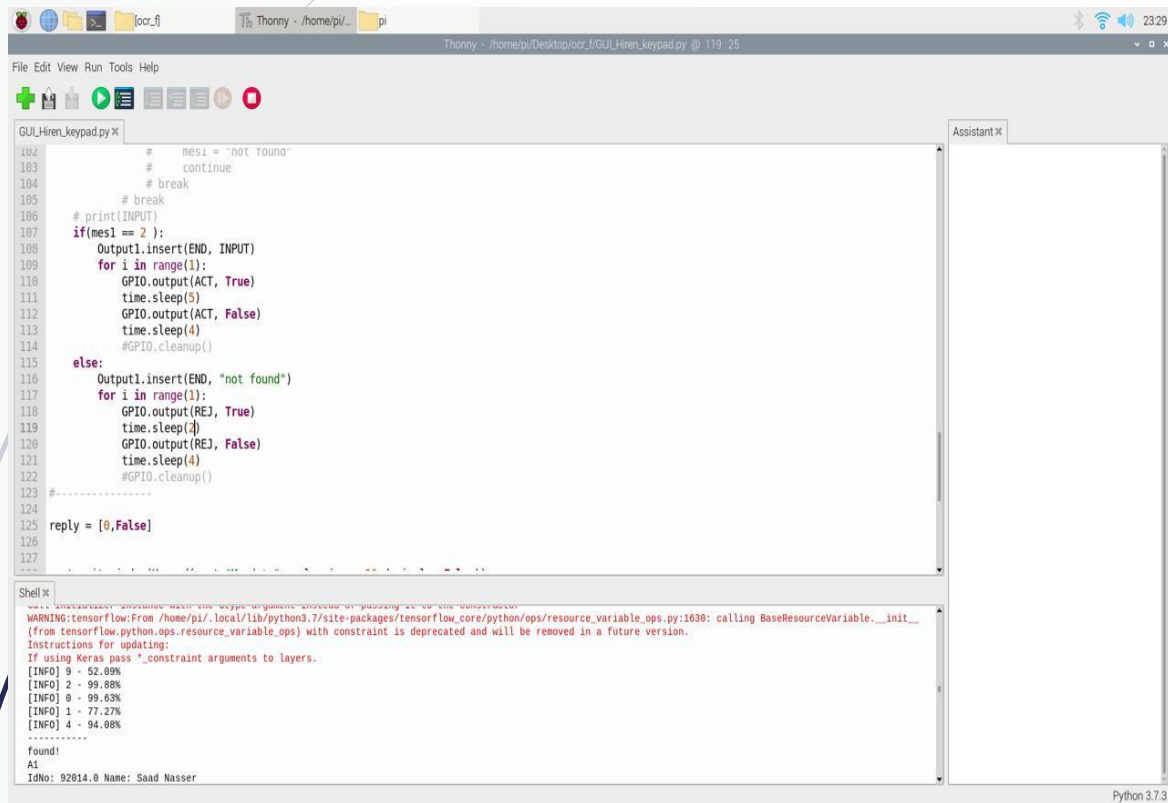
Design Subsystem II: OCR



Design Subsystem II: Raspberry Pi 4 with Camera



Design Subsystem II: Testing

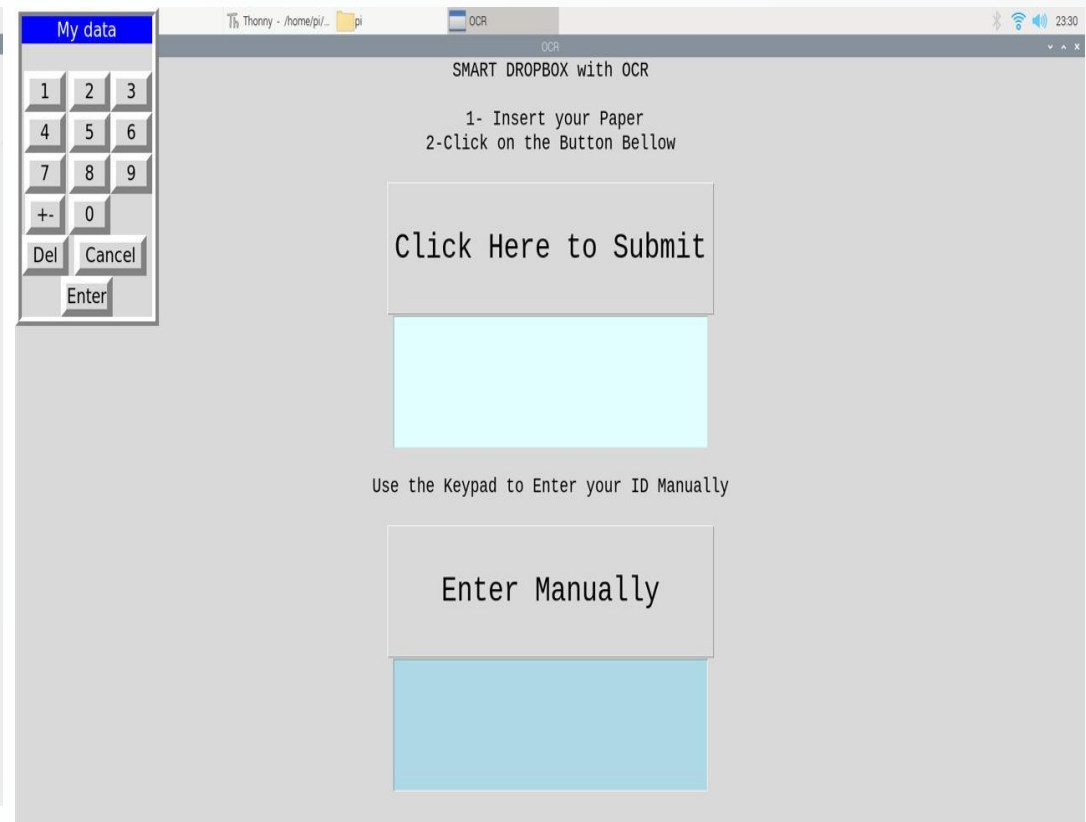


```
102     # mes1 = "not found"
103     # continue
104     # break
105     # break
106     # print(INPUT)
107     if(mes1 == 2 ):
108         Output1.insert(END, INPUT)
109         for i in range(1):
110             GPIO.output(ACT, True)
111             time.sleep(5)
112             GPIO.output(ACT, False)
113             time.sleep(4)
114             #GPIO.cleanup()
115     else:
116         Output1.insert(END, "not found")
117         for i in range(1):
118             GPIO.output(REJ, True)
119             time.sleep(2)
120             GPIO.output(REJ, False)
121             time.sleep(4)
122             #GPIO.cleanup()
123 #-----
124 reply = [0,False]
125
126
127
128
```

Shell X

```
WARNING:tensorflow:From /home/pi/.local/lib/python3.7/site-packages/tensorflow_core/python/ops/resource_variable_ops.py:1630: calling BaseResourceVariable.__init__
(from tensorflow.python.ops.resource_variable_ops) with constraint is deprecated and will be removed in a future version.
Instructions for updating:
If using Keras pass *_constraint arguments to layers.
[INFO] 9 - 52.89%
[INFO] 2 - 99.88%
[INFO] 0 - 99.63%
[INFO] 1 - 77.27%
[INFO] 4 - 94.88%
-----
found!
A1
IdNo: 92014.0 Name: Saad Nasser
```

Python 3.7.3



Design Subsystem II: Testing

```
source_variable_ops.py:1000: Cutting based on source_variable.__init__ (from tensorflow.p
source_variable_ops) with constraint is deprecated and will be removed in a future ve
Instructions for updating:
If using Keras pass *_constraints to the layer constructor instead.
[INFO] 2 - 97.03%
[INFO] 0 - 85.60%
[INFO] 1 - 97.19%
[INFO] 7 - 72.84%
[INFO] 0 - 85.50%
[INFO] 2 - 84.84%
[INFO] 2 - 98.92%
[INFO] 6 - 94.37%
[INFO] 4 - 94.47%
>>
```

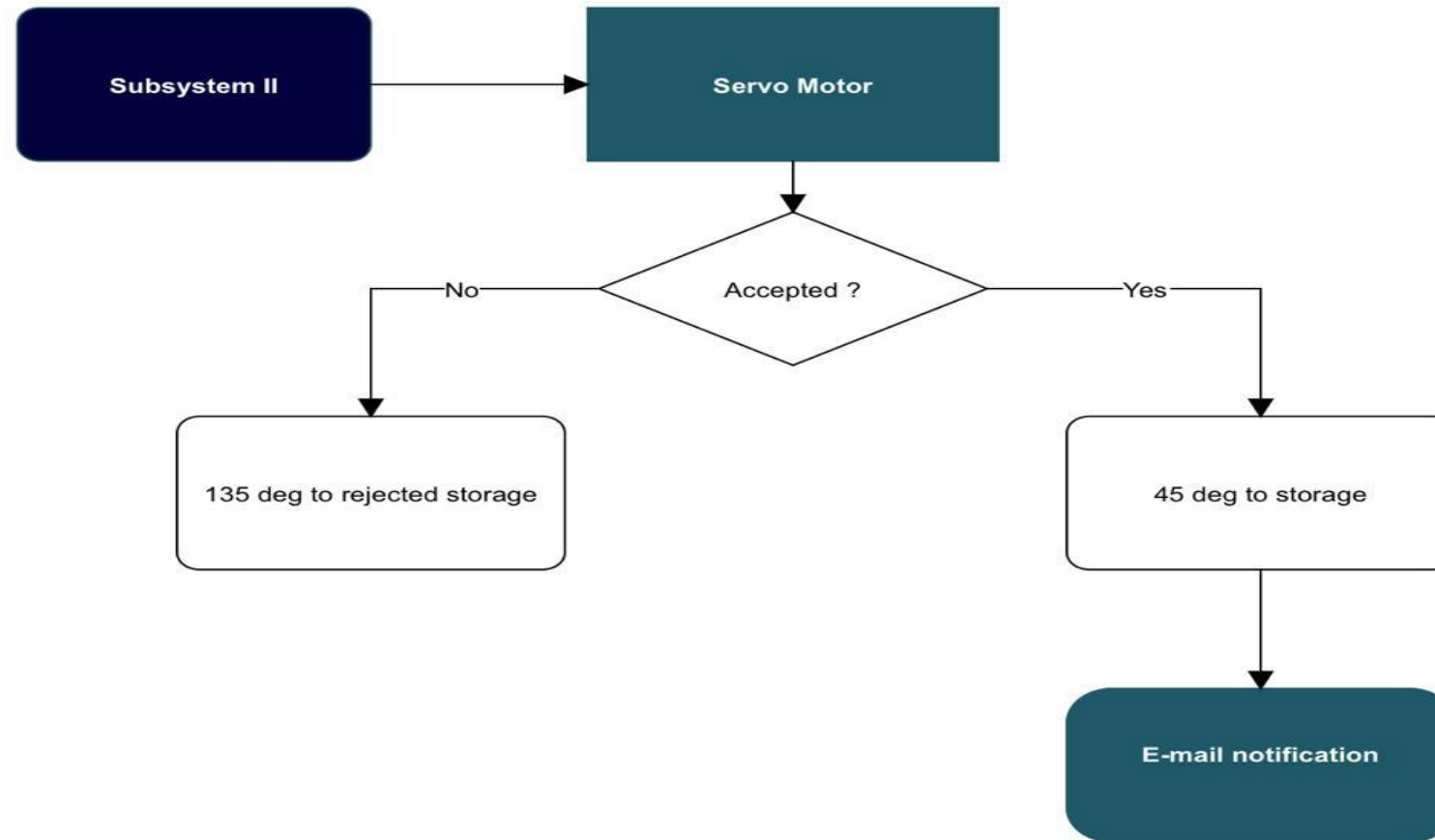


Image

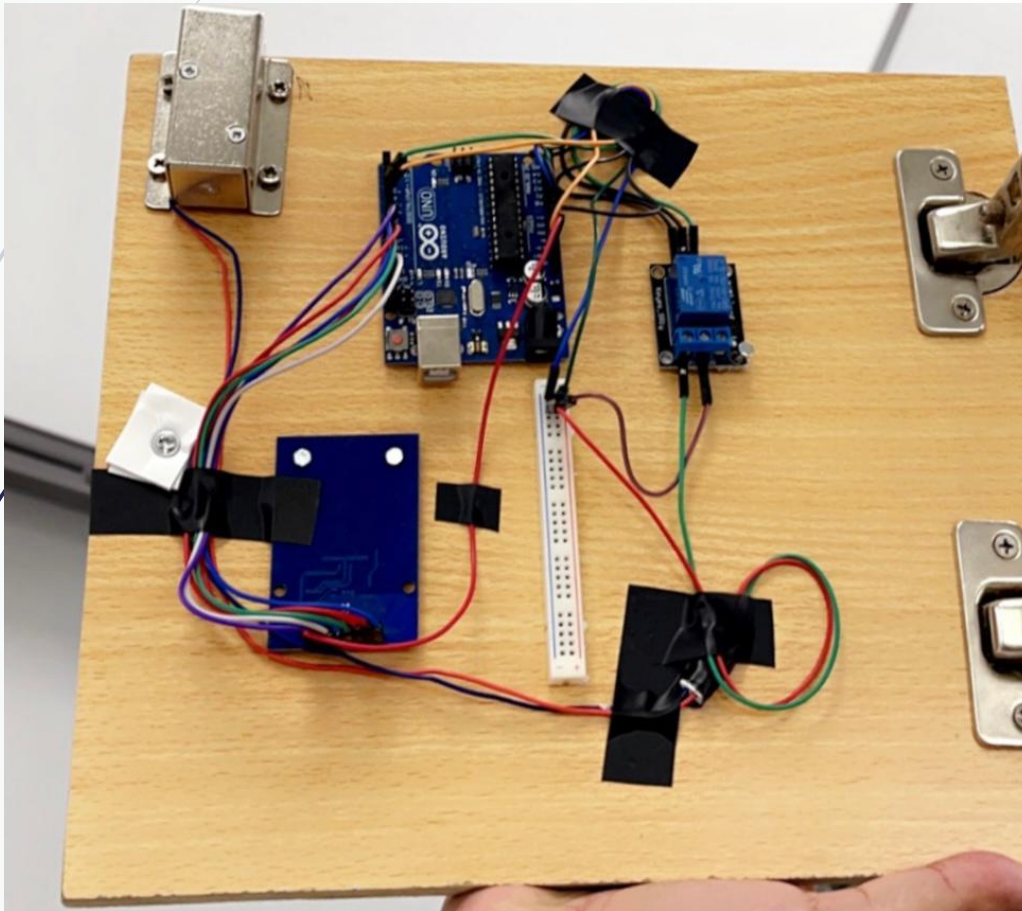
201702264

(x=241 v=9) ~ R:255 G:255 B:255

Design Subsystem III: Hardware & Software Interfacing



Design Subsystem III: Testing



Design: Completed Work

- Design subsystem I (Dropbox Design).
- Design subsystem II (OCR).
- Design subsystem III (Hardware & Software Interfacing).

Project Management and Teamwork

Task	Faisal	Adel	Saad	Bandar
Search & acquire components	25%	25%	25%	25%
Design & Implement Subsystem I	30%	30%	30%	10%
Design & Implement Subsystem II	30%	40%	20%	10%
Design & Implement Subsystem III	30%	30%	30%	10%
Testing	30%	30%	30%	10%
Write Reports & Presentations	25%	25%	25%	25%

Project Management and Teamwork

Challenges & Decision Making:

- Dropbox design.
- LCD selection.
- The movement of the rotation degree of the servo motor.

Risk Management

	Source	Events	Threats	Response
1	Servo Motor	Rotates in one direction	Not applicable with the stand	by change the type of servo motor
2	GSM Module	The module does not support email	Can not send an email notification.	Replacing the GSM module with ESP8266 NodeMCU.

Impact of COVID-19 on our project

- Social distancing.
- Online courses.

Impact of Project

- Improving the method of submission.
- Solving the conflict of students and instructors schulade.
- Secured submission.

Skills Acquired and Applied

- Cost management.
- Time management.
- Technical skills.
- Critical thinking skills.

Budget

Item	Quantity	Unit Cost (SR)	Subtotal
Raspberry Pi	1	484	484
Solenoid Lock	1	36	36
Ultrasonic Sensor	3	23	69
ESP8266	1	35	35
Dropbox	1	550	550
LCD Panel	1	345	345
Arduino Uno Board	1	45	45
LEDs	3	0.25	0.75
RFID	1	28	28
Developer Roller	1	24	24
Relay	1	45	45
H-Bridge	1	37	37
Servo Motor	1	27	27
Total		1725.75 SR	

References

- https://www.kth.se/polopoly_fs/1.987202.1589830463!/tunbergjacob_52111_2870370_The%20smart%20mailbox%20100-1.pdf
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- [http://umpir.ump.edu.my/id/eprint/12129/1/FSKKP%20-%20NAZARIAH%20ABDULLAH%20\(CD9144\).pdf](http://umpir.ump.edu.my/id/eprint/12129/1/FSKKP%20-%20NAZARIAH%20ABDULLAH%20(CD9144).pdf)
- <https://ieeexplore-ieee-org.library.pmu.edu.sa/stamp/stamp.jsp?tp=&arnumber=9262379>
- <https://www.theseus.fi/bitstream/handle/10024/159920/Smart%20Mailbox.pdf?sequence=1&isAllowed=y>

Demo Video:

➤ <https://streamable.com/01zi2m>